



Presentation at annual ERMES meeting
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LENS project L-vehicles Emissions and Noise mitigation Solutions

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Project Fiche

Grant Agreement number	101056777
Framework Programme	HORIZON Europe
Call	Clean and competitive solutions for all transport modes (Topic ID: HORIZON-CL5-2021-D5-01-16)
Type of action	Research and Innovation Action
Duration	36 months (started: 9.2022)
Budget	4 995 098 €
Total partners	15
Coordinator	Emisia S.A.

Consortium



Background

Need 1

Emissions from LVs degrade air quality in cities, but we lack **reliable emission factors** to assess their contribution, especially for some special LV subcategories

Need 2

Nanoparticles have attracted attention on their health effects, but we have very little – if any information on nanoparticle emissions from LVs, especially below 23 nm due to measurement challenges on small vehicles

Need 3

A large share of the EU population complains about **noise caused by LVs**, both in cities as well as in rural areas, such as the infamous Alpine valleys and touring routes which are popular with motorcycle riders. Measures and policy options to moderate such phenomena – further to access restrictions – are lacking

Need 4

LVs are known to be widely **tampered** by actual users and there is a need for anti-tampering measures and actual infield performance

Need 5

Emission and noise control regulations need to be inclusive of critical **operating conditions** that are prevalent in actual on-road driving of LVs causing the most impact

LENS Main Objectives

	What	Why
0.1	Beyond state-of-art LVs emission and noise measurement techniques	To be able to measure emissions and noise under real world conditions, cost-effectively
0.2	Characterise noise and pollutant emissions performance of LVs	Understand latest status of fleet emissions, identify LV subcategories that may be an issue, understand emission levels of non-regulated pollutants, feed air pollutant emission inventories and policy decision tools
0.3	In-field identification of tampered LVs	Understand the extend of the problem, identify tampering methods, provide tools and methods able to capture tampered vehicles in the field to enforce regulations
0.4	Recommendations and expected impact of decreasing noise and pollutants from LVs	Policy recommendations for various stakeholders, including regulators, national, local authorities, NGOs, etc on how emissions and noise from LVs can be decreased in the field

LENS overall methodology

In lab

PN₂₃

On road/test track

Peak events

Remotely

Tampering detection

Case studies demonstration

Case studies demonstration

Update of models

Update of models

Recommendations

Regulations E_x e_x

Surveillance

Traffic measures

Urban planning

Undesirable tampering effects

- Identified common LV modifications & tampering methods, through field research
- Identified actual frequency of modifications, through online questionnaire and face-to-face interviews with riders conducted in 20 EU MSs
- As first step, estimated modifications effects on noise and air pollution, through literature review, engineering judgement of emissions testing experts & OEMs

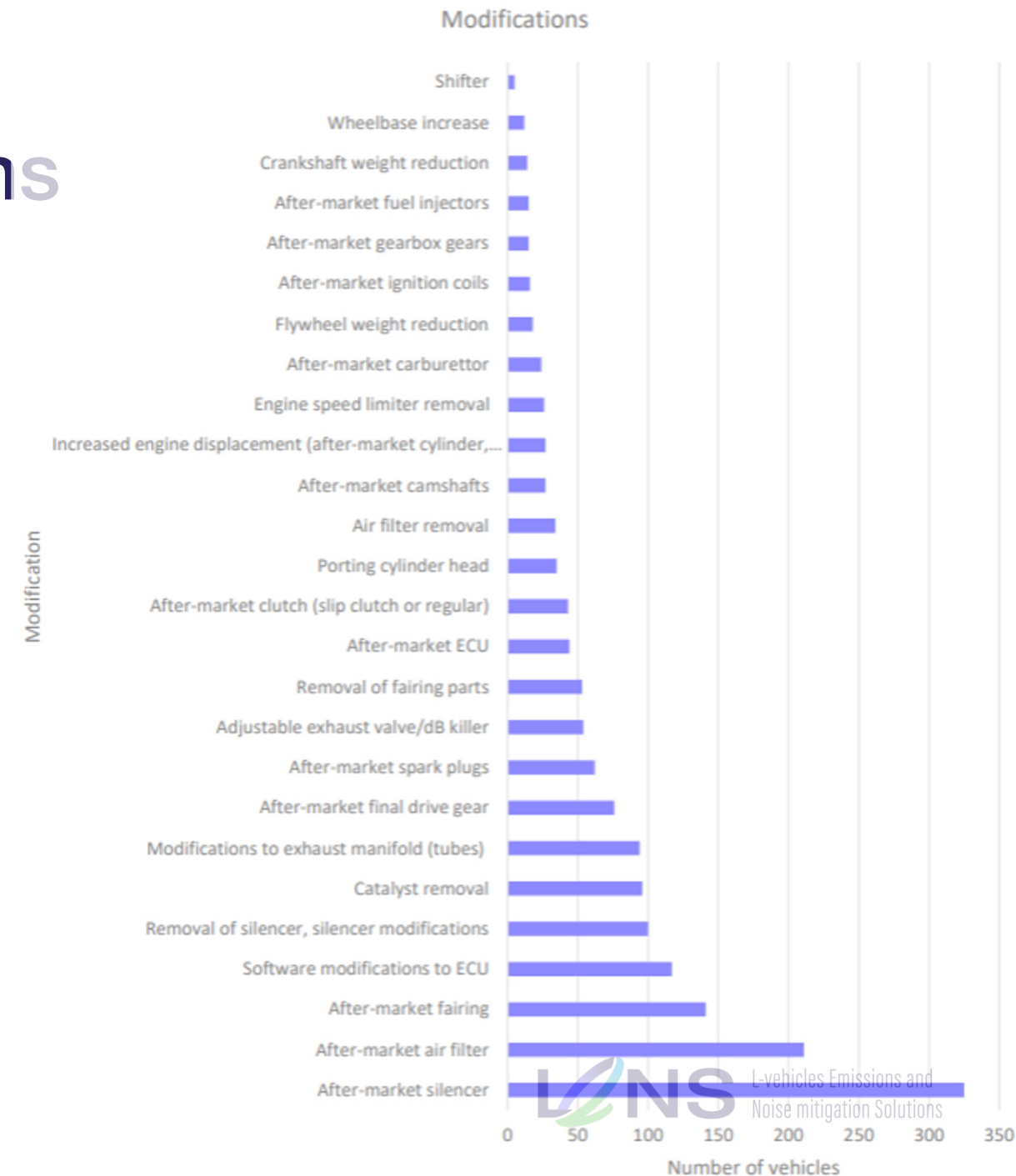
Modification	Effect on				
	CO	CO ₂	NO _x	HC	Noise level
Removal of silencer	-	-/↓	-	-	↑↑↑
Catalyst removal	↑↑↑	↓	↑↑	↑↑↑	↑
Adjustable muffler valve	-	-/↓	-	-	↑↑
Air filter removal	↓	-	↑	-/↓	↑/↑↑
After-market ECU	↑/↑↑	↑↑	↑	↑↑	↑
After-market carburettor	↑↑	↑↑	↓	↑↑↑	↑

Common tampering practices with large effects identified in LENS (D5.1)

Frequency of modifications

- More than 75% of the vehicles were not in their original configuration
- Muffler replacement was the most common practice
- Large number of vehicles with modifications that may significantly affect noise/emissions:
 - Software modified ECU (20%), removed catalyst (15%), replaced ECU (6%)

	Online Questionnaires	Face-to-face interviews	Total
Questionnaires completed	602	64	666
No modifications mentioned	157	3	160
Reviewed Questionnaires	445	61	506



Real world driving conditions and requirements for the LENS test programme

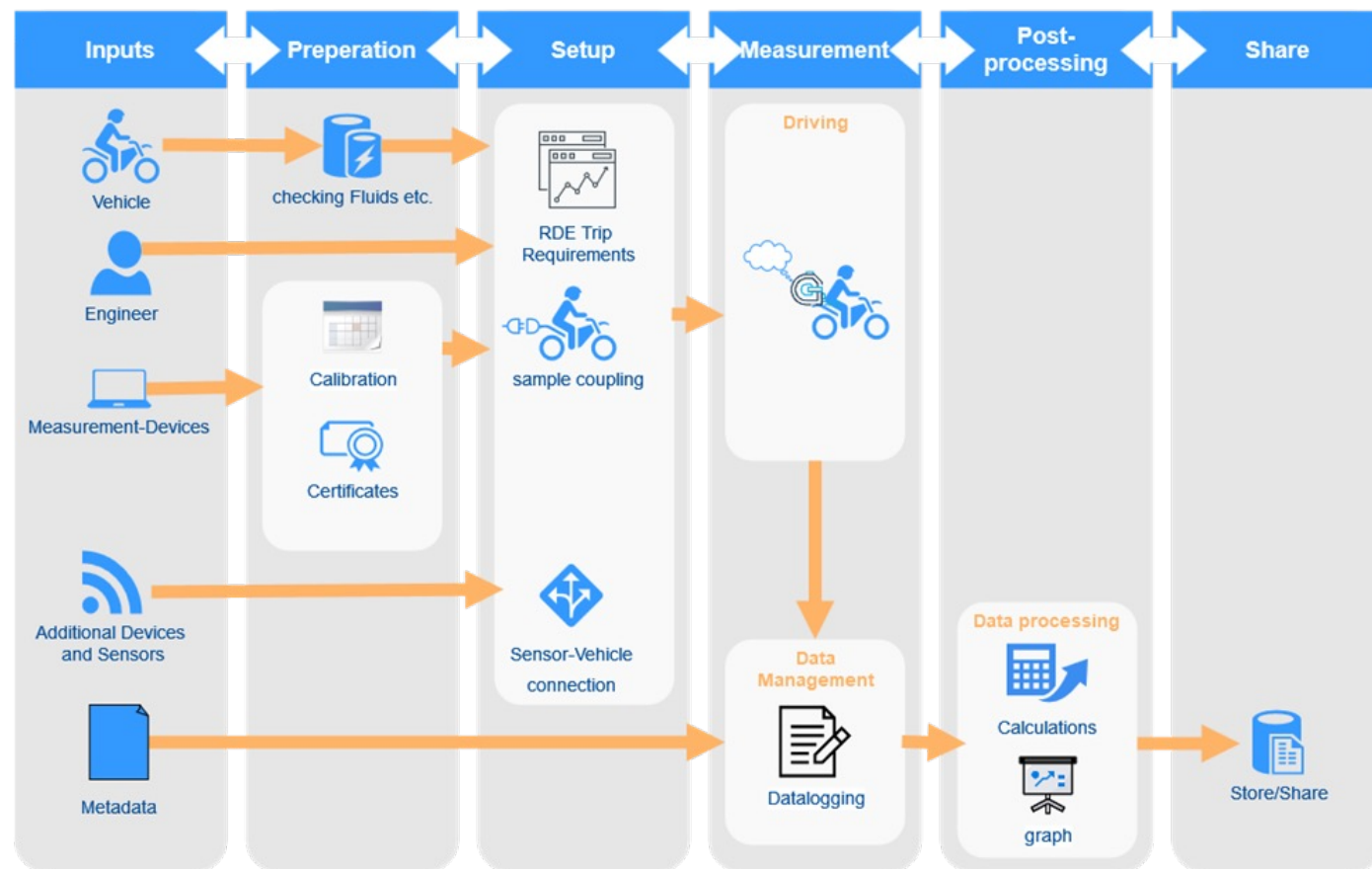
- **Literature review and analysis** of available RWD data performed to identify critical conditions for noise and pollutant emissions
- **Roadside measurements** performed to verify conditions
- Recommendations provided to include in the **LENS test programme**
- Recommendations **of data** that have to be recorded during measurements

- ❖ Cold engine start
- ❖ Driving at max rated speed (mainly for mopeds)
- ❖ Strong accelerations, including from standstill
- ❖ Transition from constant speed or acceleration phases to deceleration phases
- ❖ Restarting during the test
- ❖ Testing at max technically permissible mass
- ❖ Stop and go testing simulating traffic congestion
- ❖ Engine revving

Recommendations for testing conditions in LENS (D6.1)

On-board measurement protocol definitions

- Standards and procedure for on-road measurements within LENS
- Tests with various on-board suitable measurement equipment
- Definition of RDE trip requirements
- Suggestions for future test protocols



Systems and challenges for on-board emission measurements

Systems available:

- Standard automotive PEMS with EFM
- SEMS with selected sensors for NO_x, CO₂, CO, NH₃, O₂, HC, BC, PM, ...
- On-board FTIR

Challenges to be addressed:

- Can-bus access for vehicle data (rpm, gear, ...)
- Difficult access to exhaust gas at tailpipe
- Exhaust gas flow measurement
- Suitability of measurement systems for small LVs

Method and system for on-board noise measurement



[1]

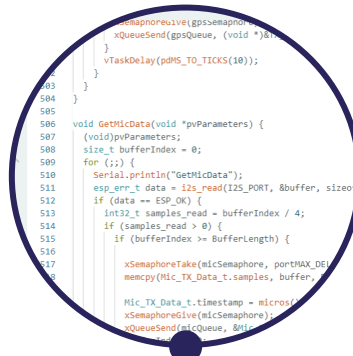
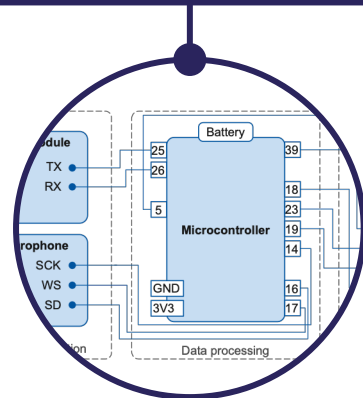
Components

Selection

- Microcontroller
- GPS Module
- Microphone
- SD card module

Wiring & Soldering

- Drawing of circuit diagram
- Soldering of components



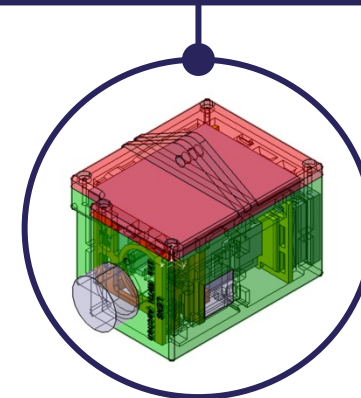
Software

Development & Implementation

- Arduino IDE

Mechanical housing design

- CATIA Software



3D Print

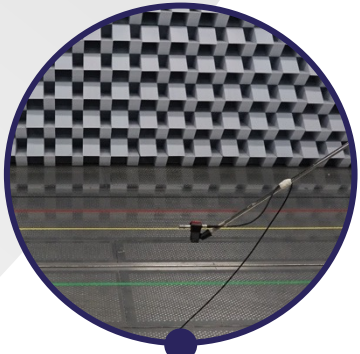
3D Printing

- Material: PA12

Inserting of components

[1] <https://www.dfrobot.com/product-1590.html>

Method and system for on-board noise measurement



Measurements

- Identification of suitable sensor position on L-category vehicles

Verification

Comparison

- MEMS Microphone and microphone of a high accuracy class in semi-anechoic chamber

Sensor position



Measurement campaign

Purpose

- Detection of driving scenarios that cause high noise emissions
- Mounting of sensor system on 14 L-category vehicles
- Definition of real-world driving cycles

Conclusion

- Sensor system is suitable for on-road (on-board) measurements in comparison to a microphone of a high accuracy class
- A suitable mounting position on L-category vehicles could be found

➔ **Measurement campaign can start**

Overall status and path

- Main testing campaign in the lab has started (in total: 150 LVs)
- On road SEMS systems are being finalized for on-road tests
- Evaluation protocol and database for storing measured data finalized
- 3 Remote sensing campaigns are being planned for 2024
- Impact assessment of different approaches being planned



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Brussels, 5-7.2.2024

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